## Stability Property and Separation Condition in an Almost Periodic Integrodifferential Equation

## Yoshihiro HAMAYA

Department of Applied Science, Faculty of Science,
Okayama University of Science, 1-1 Ridaicho, Okayama 700 Japan
(Received September 30, 1990)

In order to discuss the existence of an almost periodic solution in an integrodifferential equation with infinite delay, we have discussed the relationship between the total stability with respect to a certain metric  $\rho$  and the separation condition with respect to  $\rho$  2).

In this paper, we shall discuss a relationship between the  $\rho$ -separation condition and uniformly asymptotic stability property in a certain sense.

We shall consider a system of integrodifferential equations

$$\dot{x}(t) = f(t, x(t)) + \int_{-\infty}^{0} F(t, s, x(t+s), x(t)) ds,$$
 (1)

where  $f: R \times R^n \to R^n$  is continuous and is almost periodic in t uniformly for  $x \in R^n$ , and F(t, s, x, y) is continuous on  $R \times (-\infty, 0] \times R^n \times R^n$  and is almost periodic in t uniformly for  $(s, x, y) \in R^* = (-\infty, 0] \times R^n \times R^n$ . For the definition and the properties of almost periodic functions with parameters, see 4). If x is a function defined on  $(-\infty, a)$ ,  $x_t$  is defined by the relation  $x_t(s) = x(t+s)$ ,  $-\infty < s \le 0$ . Let |x| be any norm of x in  $R^n$ . BC denotes the vector space of bounded continuous functions mapping  $(-\infty, 0]$  into  $R^n$ , and for any  $\phi$ ,  $\psi \in BC$ , we set

$$\rho(\phi, \ \psi) = \sum_{m=1}^{\infty} \rho_m(\phi, \ \psi) / [2^m(1 + \rho_m(\phi, \ \psi))],$$

where  $\rho_m(\phi, \phi) = \sup_{-m \le s \le 0} |\phi(s) - \psi(s)|$ . Clearly,  $\rho(\phi^k, \phi) \to 0$  as  $k \to \infty$  if and only if  $\phi^k(s) \to \phi(s)$  uniformly on any compact subset of  $(-\infty, 0]$  as  $k \to \infty$ . Moreover, we denote by  $(BC, \rho)$  the space of bounded continuous functions  $\phi: (-\infty, 0] \to R^n$  with metric  $\rho$ .

For system (1), we make the following assumptions:

(H<sub>1</sub>) For any  $\varepsilon > 0$  and any compact set B in  $\mathbb{R}^n$ , there exists an  $S = S(\varepsilon, B) > 0$ 

such that

$$\int_{-\infty}^{-S} |F(t, s, x(t+s), x(t))| ds \le \varepsilon \text{ for all } t \in \mathbb{R},$$

whenever  $x(\sigma)$  is continuous and  $x(\sigma) \in B$  for all  $\sigma \le t$ .

(H<sub>2</sub>) System (1) has a bounded solution u(t) defined on  $[0, \infty)$  which passes through  $(0, \phi^0), \phi^0 \in BC$ .

Remark 1. It follows from  $(H_1)$  that for any compact set B in  $\mathbb{R}^n$ , there exists an L(B) > 0 such that

$$\int_{-\infty}^{0} |F(t, s, x(t+s), x(t))| ds \leq L(B) \text{ for all } t \in \mathbb{R},$$

whenever  $x(\sigma)$  is continuous and  $x(\sigma) \in B$  for all  $\sigma \le t$ . Moreover,

 $\int_{-\infty}^{0} F(t, s, x(t+s), x(t)) ds \text{ is continuous in } t, \text{ whenever } x(\sigma) \text{ is continuous and bounded for } \sigma \leq t.$ 

Under assumption  $(H_1)$ , for any  $t_0 \in R$  and any  $\phi \in BC$ , there exists a solution of (1) which passes through  $(t_0, \phi)$ . Moreover, a solution x(t) can be continuable up to  $t = \infty$  if it remains in a compact set in  $R^n$ .

Denote by  $\Omega(f, F)$  the set of all limiting functions (g, G) such that for some sequence  $\{t_k\}$ ,  $t_k \to \infty$  as  $k \to \infty$ ,  $f(t+t_k, x) \to g(t, x)$  uniformly on  $R \times S$  for any compact subset S in  $R^n$  and  $F(t+t_k, s, x, y) \to G(t, s, x, y)$  uniformly on  $R \times S^*$  for any compact subset  $S^*$  in  $R^*$  as  $k \to \infty$ . Then a system

$$\dot{x}(t) = g(t, x(t)) + \int_{-\infty}^{0} G(t, s, x(t+s), x(t)) ds$$
 (2)

is called a limiting equation of (1) when  $(g, G) \in \Omega(f, F)$ . Clearly, if  $(g, G) \in \Omega(f, F)$ , g(t, x) is almost periodic in t uniformly for  $x \in \mathbb{R}^n$  and G(t, s, x, y) is almost periodic in t uniformly for  $(s, x, y) \in \mathbb{R}^*$ .

Remark 2. When F(t, s, x, y) satisfies condition  $(H_1)$ , any  $G \in \Omega(F)$  satisfies condition  $(H_1)$  for the same  $S = S(\varepsilon, B) > 0$  as for F, that is,

$$\int_{-\infty}^{-s} |G(t, s, x(t+s), x(t))| ds \le \varepsilon \text{ for all } t \in R,$$

whenever  $x(\sigma)$  is continuous and  $x(\sigma) \in B$  for all  $\sigma \le t$ .

Let K be a compact set in  $R^n$  such that  $u(t) \in K$  for all  $t \in R$ , where  $u(t) = \phi^0(t)$  for t < 0. If x(t) is a solution such that  $x(t) \in K$  for all  $t \in R$ , we say that x is

in K.

Definition 1. We say that system (1) satisfies the  $\rho$ -separation condition in K, if for each  $(g, G) \in \Omega(f, F)$ , there exists a  $\lambda(g, G) > 0$  such that if x and y are distinct solutions of (2) in K, then we have

$$\rho(x_t, y_t) \ge \lambda(g, G) \text{ for all } t \in \mathbb{R}.$$
 (3)

If system (1) satisfies the  $\rho$ -separation condition in K, then we can choose a positive constant  $\lambda_0$  independent of (g, G) for which  $\rho(x_t, y_t) \ge \lambda_0$  for all  $t \in R$ , where x and y are distinct solutions of (2) in K. We shall call  $\lambda_0$  the  $\rho$ -separation constant in K.

Definition 2. A solution x(t) of (1) in K is said to be relatively totally  $(K, \rho)$ stable, if for any  $\varepsilon > 0$  there exists a  $\delta(\varepsilon) > 0$  such that  $\rho(x_t, y_t) < \varepsilon$  for all  $t \ge t_0$  whenever  $\rho(x_{t_0}, y_{t_0}) < \delta(\varepsilon)$  at some  $t_0 \in R$  and p(t) is any continuous function which satisfies  $|p(t)| < \delta(\varepsilon)$  for  $t \ge t_0$ . Here y is a solution through  $(t_0, y_{t_0})$  of

$$\dot{x}(t) = f(t, x(t)) + \int_{-\infty}^{0} F(t, s, x(t+s), x(t)) ds + p(t)$$

such that  $y_{t_0}(s) \in K$  for  $s \le 0$  and  $y(t) \in K$  for  $t \ge t_0$ .

In the case where  $p(t) \equiv 0$ , this gives the definition of the relative uniform  $(K, \rho)$ -stability of x(t).

Hamaya and Yoshizawa 2) have obtained the following result.

Proposition. Under assumptions  $(H_1)$  and  $(H_2)$ , if system (1) satisfies the  $\rho$ -separation condition in K, then for any  $(g, G) \in \Omega(f, F)$ , any solution x of (2) in K is relatively totally  $(K, \rho)$ -stable. Moreover, we can choose the number  $\delta(\bullet)$  in Definition 2 so that  $\delta(\varepsilon)$  depends only on  $\varepsilon$  and is independent of (g, G) and solutions.

Theorem 1. Under assumptions  $(H_1)$  and  $(H_2)$ , suppose that system (1) satisfies the  $\rho$ -separation condition in K. If w(t) is a solution of (1) such that  $w(t) \in K$  for all  $t \in R$ , then w(t) is almost periodic.

*Proof.* By proposition, solution w(t) of (1) is relatively totally  $(K, \rho)$ -stable,

because  $(f, F) \in \Omega(f, F)$ . Then w(t) is asymptotically almost periodic on  $[0, \infty)$  by Theorem 1 in 1). Thus, it has the decomposition w(t) = p(t) + q(t), where p(t) is almost periodic in t, q(t) is continuous and  $q(t) \to 0$  as  $t \to \infty$ . Since  $w(t) \in K$  for all  $t \in R$ , p(t) is a solution of (1) in K. If  $w(t_1) \neq p(t_1)$  at some  $t_1$ , we have two distinct solutions of (1) in K. Thus we have  $\rho(w_t, p_t) \ge \lambda_0 > 0$  for all  $t \in R$ , where  $\lambda_0$  is the  $\rho$ -separation constant. However,  $w(t) - p(t) \to 0$  as  $t \to \infty$ , and hence  $\rho(w_t, p_t) \to 0$  as  $t \to \infty$ . This contradiction shows  $w(t) \equiv p(t)$  for all  $t \in R$ .

Definition 3. A solution x(t) of (1) in K is said to be relatively uniformly asymptotically  $(K, \rho)$ -stable, if it is relatively uniformly  $(K, \rho)$ -stable and if there exists a  $\delta_0 > 0$  and for any  $\varepsilon > 0$  there exists a  $T(\varepsilon) > 0$  such that if  $\rho(x_{t_0}, y_{t_0}) < \delta_0$  at some  $t_0 \in R$ , then  $\rho(x_t, y_t) < \varepsilon$  for all  $t \ge t_0 + T(\varepsilon)$ , where y is a solution through  $(t_0, y_{t_0})$  of (1) such that  $y_{t_0}(s)$  for  $s \le 0$  and  $y(t) \in K$  for all  $t \ge t_0$ .

We shall show that the  $\rho$ -separation condition will be characterized in terms of relatively uniformly asymptotic  $(K, \rho)$ -stability of solutions in K of limiting equations. For ordinary differential equations, this kind of problems has been discussed by Nakajima 3).

Theorem 2. Under assumptions  $(H_1)$  and  $(H_2)$ , system (1) satisfies the  $\rho$ -separation condition in K if and only if for any  $(g, G) \in \Omega(f, F)$ , any solution x of (2) in K is relatively uniformly asymptotically  $(K, \rho)$ -stable with a common triple  $(\delta_0, \delta(\bullet), T(\bullet))$ .

Proof. We suppose that system (1) satisfies the  $\rho$ -separation condition in K. Then it follows from proposition 1 that for any  $\varepsilon > 0$ , there exists a  $\delta(\varepsilon) > 0$  such that for any  $(g, G) \in \Omega(f, F)$  and any solution x(t) of (2) in K, if  $\rho(x_{t_0}, y_{t_0}) < \delta(\varepsilon)$  at some  $t_0 \in R$ , then  $\rho(x_t, y_t) < \varepsilon$  for all  $t \ge t_0$ , where y(t) is a solution of (2) such that  $y_{t_0}(s) \in K$  for  $s \le 0$  and  $y(t) \in K$  for  $t \ge t_0$ . Now let  $\delta_0$  be a positive constant such that  $\delta_0 < \delta(\lambda_0/2)$ , where  $\lambda_0$  is the  $\rho$ -separation constant. For this  $\delta_0$ , we shall show that for any  $\varepsilon > 0$ , there exists a  $T(\varepsilon) > 0$  such that for any  $(g, G) \in \Omega(f, F)$  and any solution x(t) of (2) in K,  $\rho(x_t, y_t) < \varepsilon$  for all  $t \ge t_0 + T(\varepsilon)$  whenever  $\rho(x_{t_0}, y_{t_0}) < \delta_0$  at some  $t_0 \in R$ , where y(t) is a solution of (2) such that  $y_{t_0}(s) \in K$  for all  $s \le 0$  and  $y(t) \in K$  for all  $t \ge t_0$ .

Suppose not. Then there exists an  $\varepsilon$ ,  $0 < \varepsilon < \delta_0/2$ , and sequences  $\{(g_k, G_k)\}$ ,  $\{x^k\}$ ,  $\{y^k\}$ ,  $\{s_k\}$  and  $\{t_k\}$  such that  $(g_k, G_k) \in \Omega(f, F)$ ,  $x^k(t)$  is a solution in K of

$$\dot{x}(t) = g_k(t, x(t)) + \int_{-\infty}^{0} G_k(t, s, x(t+s), x(t)) ds$$
 (4)

and that  $t_k \ge s_k + k$ ,

$$\rho(x_{s_i}^k, y_{s_i}^k) < \delta_0 < \delta(\lambda_0/2) \tag{5}$$

and

$$\rho(x_{t_k}^k, y_{t_k}^k) \ge \varepsilon, \tag{6}$$

where  $y^k(t)$  is a solution of (4) such that  $y^k_{s_k}(s) \in K$  for all  $s \le 0$  and  $y^k(t) \in K$  for all  $t \ge s_k$ . Since (5) implies  $\rho(x^k_t, y^k_t) < \lambda_0/2$  for all  $t \ge s_k$ , we have

$$\varepsilon \le \rho(x_{t_1}^k, y_{t_1}^k) \le \lambda_0/2. \tag{7}$$

If we set  $w^k(t) = x^k(t+t_k)$  and  $z^k(t) = y^k(t+t_k)$ , then  $w^k(t)$  is a solution in K of

$$\dot{x}(t) = g_k(t + t_k, x(t)) + \int_0^0 G_k(t + t_k, s, x(t+s), x(t)) ds$$
 (8)

and  $z^k(t)$  is defined for  $t \ge -k$  and is a solution of (8) such that  $z^k_{-k}(s) \in K$  for all  $s \le 0$  and  $z^k(t) \in K$  for all  $t \ge -k$ . Since  $(g_k(t+t_k, x), G_k(t+t_k, s, x, y)) \in \Omega(f, F)$ , taking a subsequence if necessary, we can assume that  $w^k(t) \to w(t)$  uniformly on any compact interval in R,  $z^k(t) \to z(t)$  uniformly on any compact interval in R,  $g_k(t+t_k, x) \to h(t, x)$  uniformly on  $R \times K$  and  $G_k(t+t_k, s, x, y) \to H(t, s, x, y)$  uniformly on  $R \times S^* \times K \times K$  for any compact set  $S^*$  in  $(-\infty, 0]$  as  $k \to \infty$ , where  $(h, H) \in \Omega(f, F)$ . Then, by the same argument as in the proof of Lemma 2 in 2), w(t) and z(t) are solutions in K of

$$\dot{x}(t) = h(t, x(t)) + \int_{-\infty}^{\infty} H(t, s, x(t+s), x(t)) ds.$$
 (9)

On the other hand, we have

$$\rho(w_0, z_0) = \lim_{k \to \infty} \rho(w_0^k, z_0^k) = \lim_{k \to \infty} \rho(x_{t_k}^k, y_{t_k}^k).$$

Thus, it follows from (7) that

$$\varepsilon \le \rho(w_0, z_0) \le \lambda_0/2.$$
 (10)

Since w(t) and z(t) are distinct solutions of (9) in K, (10) contradicts the  $\rho$ separation condition. This shows that for any  $(g, G) \in \Omega(f, F)$ , any solution xof (2) in K is relatively uniformly asymptotically  $(K, \rho)$ -stable with a common
triple  $(\delta_0, \delta(\bullet), T(\bullet))$ .

Now we assume that for any  $(g, G) \in \Omega(f, F)$ , any solution of (2) in K is

relatively uniformly asymptotically  $(K, \rho)$ -stable with a common triple  $(\delta_0, \rho(\bullet), T(\bullet))$ . First of all, we shall see that any two distinct solutions x(t) and y(t) in K of a limiting equation of (1) satisfy

$$\lim_{t \to -\infty} \rho(x_t, y_t) \ge \delta_0. \tag{11}$$

Suppose not. Then for some  $(g, G) \in \Omega(f, F)$ , there exist two distinct solutions x(t) and y(t) of (2) in K which satisfy

$$\lim_{t \to -\infty} \rho(x_t, y_t) < \delta_0. \tag{12}$$

Since  $x(t) \not\equiv y(t)$ , we have  $|x(t_0) - y(t_0)| = \varepsilon > 0$  at some  $t_0$ . Thus we have  $\rho(x_{t_0}, y_{t_0}) \ge \varepsilon / 2(1+\varepsilon)$ . By (12), there exists a  $t_1$  such that  $\rho(x_{t_1}, y_{t_1}) < \delta_0$  and  $t_1 < t_0 - T(\varepsilon / 4(1+\varepsilon))$ , where  $T(\bullet)$  is the number for relatively uniformly asymptotic  $(K, \rho)$ -stability. Since x(t) is relatively uniformly asymptotically  $(K, \rho)$ -stable, we have  $\rho(x_{t_0}, y_{t_0}) < \varepsilon / 4(1+\varepsilon)$ , which contradicts  $\rho(x_{t_0}, y_{t_0}) \ge \varepsilon / 2(1+\varepsilon)$ . Thus we have (11).

For any solution x(t) in K, there exist positive constants c and  $L^*$  such that  $|x(t)| \le c$  and  $|x(t)| \le L^*$  for all  $t \in R$ . Denote by X the set

$$X = \{ \phi \in BC : \phi(s) \text{ is a function such that } |\phi(s)| \le c \text{ for } s \in (-\infty, 0]$$
 and  $|\phi(s_1) - \phi(s_2)| \le L^* |s_1 - s_2| \text{ for all } s_1, s_2 \in (-\infty, 0] \}.$ 

Then X is compact in  $(BC, \rho)$ . Thus, there are finite number of coverings which consist of  $m_0$  balls with diameter  $\delta_0/4$ . We shall see that the number of distinct solutions of (2) in K is at most  $m_0$ . Suppose that there are  $m_0+1$  distinct solutions  $x^{(j)}(t)$   $(j=1, 2, \dots, m_0+1)$ . By (11), there exists a  $t_2$  such that

$$\rho(x_{t_2}^{(i)}, x_{t_2}^{(j)}) \ge \delta_0/2 \text{ for } i \ne j.$$
 (13)

Since  $x_{t_2}^{(j)}$ ,  $j=1, 2, \dots, m_0+1$  are in X, some two of these, say  $x_{t_2}^{(i)}$ ,  $x_{t_2}^{(j)}$ ,  $(i \neq j)$ , are in one ball and hence  $\rho(x_{t_2}^{(i)}, x_{t_2}^{(j)}) < \delta_0/4$ , which contradicts (13). Therefore the number of solutions of (2) in K is  $m \leq m_0$ . Thus we have the set of solutions of (2) in K

$$\{x^{(1)}(t), x^{(2)}(t), \dots, x^{(m)}(t)\}$$

and

$$\lim_{t \to -\infty} \rho(x_t^{(i)}, x_t^{(j)}) \ge \delta_0 \text{ for } i \ne j.$$
(14)

Consider a sequence  $\{t_k\}$  such that  $t_k \to -\infty$ ,  $g(t+t_k, x) \to g(t, x)$  uniformly on

 $R \times K$  and  $G(t+t_k, s, x, y) \rightarrow G(t, s, x, y)$  uniformly on  $R \times S^* \times K \times K$  for any compact set  $S^*$  in  $(-\infty, 0]$  as  $k \rightarrow \infty$ . Since the sequences  $\{x^{(j)}(t+t_k)\}$ ,  $1 \le j \le m$ , are uniformly bounded and equicontinuous, there exists a subsequence of  $\{t_k\}$ , which will be denoted by  $\{t_k\}$  again, and functions  $y^{(j)}(t)$  such that  $x^{(j)}(t+t_k) \rightarrow y^{(j)}(t)$  uniformly on any compact interval in R as  $k \rightarrow \infty$ . Clearly  $y^{(j)}(t)$  is solution of (2) in K. Since we have

$$\rho(y_t^{(i)}, y_t^{(j)}) = \lim_{k \to \infty} \rho(x_{t+t_k}^{(i)}, x_{t+t_k}^{(j)}) \text{ for } t \in R,$$

it follows from (14) that

$$\rho(y_t^{(i)}, y_t^{(j)}) \ge \delta_0 \text{ for all } t \in R \text{ and } i \ne j.$$

Since we have (15), distinct solutions of (2) in K are  $y^{(1)}(t)$ ,  $y^{(2)}(t)$ , ...,  $y^{(m)}(t)$ . This shows that system (1) satisfies the  $\rho$ -separation condition in K with the  $\rho$ -separation constant  $\delta_0$ .

## References

- 1) Y. Hamaya, Total stability property in limiting equations of integrodifferential equations, Funkcial. Ekvac., 33 (1990), 345-362.
- 2) Y. Hamaya and T. Yoshizawa, Almost periodic solutions in an integrodifferential equation, Proc. Roy. Soc. Edinburgh (to appear).
- 3) F. Nakajima, Separation conditions and stability properties in almost periodic systems, Tohoku Math. J., 26 (1974), 305-314.
- 4) T. Yoshizawa, Stability Theory and the Existence of Periodic Solutions and Almost Periodic Solutions, Applied Math. Science, Vol. 14, Springer-Verlag, New York 1975.